## SPD-482500BRUSHLESS 48 Volt DC 2000-2500 Watt Brushless DC Motor Controller

Operating Voltage: 48 Volts DC (Works with 48V Battery Packs) Power: Works with 2000-2500 Watt Brushless DC Motors

Current Limit: 65 Amps (65 Amps 3125 Watts Maximum Current Output)

Low Voltage Protection: 42.5 Volts

Works with both Sensored and Sensorless Brushless DC Motors Compatible with 120 Degree and 60 Degree Motor Phases

Power Switch Wires	Purple to Power Switch Contact Red to Power Switch Contact
Input Power Wires	Red Wire to Battery Positive + Black Wire to Battery Negative -
Motor Phase Wires	Yellow to Yellow Motor Phase U Wire Blue to Blue Motor Phase V Wire Green to Green Motor Phase W Wire
† Motor Hall Sensor Wires	Red to Red Motor Hall Wire +5V Black to Black Motor Hall Wire GND Yellow to Yellow Motor Hall U Wire Green to Green Motor Hall V Wire Blue to Blue Motor Hall W Wire
* Throttle Wires	Red +5 Volt Output Green 1-4 Volt Signal Input Black Ground
† 3 Speed Control Wires	Orange High Speed Black Medium Speed Blue Low Speed  BLK to ORG = High BLK to BLK = Med BLK to BLU = Low
† Cruise Control Wires	Pink to Cruise Control Switch Contact Black to Cruise Control Switch Contact
† Reverse Wires	Brown to Reverse Switch Contact Black to Reverse Switch Contact
† Low Level E-Brake Wires	White to Low Level Brake Switch Contact Black to Common Brake Switch Contact
† High Level E-Brake Wires	Yellow to High Level Brake Switch Contact
* Pedal Assist Sensor Wires	Red +5 Volt Output Blue 1-4 Volt Signal Input Black Ground
† Regen Braking Wires	Orange to Regen Braking Switch Contact Orange to Regen Braking Switch Contact
** Self Learning Wires	Connect Together for Self Learning Mode Disconnect After Self Learning Is Completed

<sup>†</sup> Optional Connections: These wires do not need to be connected for the controller to operate.

<sup>\*</sup> Either the Throttle and or Pedal Assist Sensor needs to be connected for the controller to operate.

<sup>\*\*</sup> The Self Learning Wires can be connected to train the controller to operate with the motor that it is attached to and then disconnected after the training has been completed.